FARO[®] Laser Scanner Focus^{3D} X 130 HDR The Imaging Laser Scanner





HDR PHOTO OVERLAY

With the Focus3D HDR you will now master challenging lighting conditions. Predefined HDR profiles increase the picture quality recorded in very bright or dark environments.

HD PHOTO RESOLUTION

The increased camera resolution of Focus^{3D} X 130 HDR delivers extraordinary color overlays for scanned point clouds. This improves the visualization of important details on site.

XTRA PORTABLE

The Focus^{3D} X 130 HDR has the size of only 24 x 20 x 10 cm and a weight of just 5.2kg. Waterproof Pelicase and a ergonomic backpack incl. tripod holder make the device truly portable.

MID RANGE SCANNING - UP TO 130M

The 130m range allows the Focus3D X 130 HDR to scan in all kinds of applications in the architecture, BIM, heritage, forensics, shipbuilding, construction and process industries.

XTRA POSITIONING - INTEGRATED GPS RECEIVER

Effortlessly determine the position of the scanner. This helps to facilitate the registration process and provides the exact time and location of the users' scans.

X-SERIES HDR LASER SCANNER FOR MID-RANGE APPLICATIONS

The X-series laser scanner FARO Focus^{3D} X 130 HDR is a powerful high-speed 3D scanner delivering realistic and true-to-detail scan results.

The ultra-portable Focus^{3D} X 130 HDR enables fast, straightforward, and yet accurate measurements of façades, complex structures, production and supply facilities, accident sites, and large-volume components. Combining the highest-precision scanning technology with authentic mobility and ease-of-use, the device offers reliability, flexibility, and real-time views of recorded data. The 3D scan data can easily be imported into all commonly used software solutions for accident reconstruction, architecture, civil engineering, construction, forensics or industrial manufacturing.

With a battery runtime of 4.5 hours, the laser scanner has also a high level of flexibility and endurance. The Focus' light weight, small size and SD-card makes the scanner truly mobile.

BENEFITS

- Safe and fast as-built data capturing with superior color detail
- Reliable life-like visualization, even under extreme lighting conditions
- Reduced complexity by integrated scanning and imaging workflow for all kinds of measurements even in challenging environments
- Increased onsite productivity due to one person operation
- Revolutionary price/performance ratio, as all-in-one device



PERFORMANCE SPECIFICATIONS

Ranging unit

Unambiguity interval: Range: Measurement speed (pts/sec): Ranging error¹:

By 122 till 488 Kpts/sec at 614m; by 976 Kpts/sec at 307m 0.6m - 130m indoor or outdoor with upright incidence to a 90% reflective surface 122,000 / 244,000 / 488,000 / 976,000 ±2mm

Ranging noise ²	@10m	@10m - noise compressed ³	@25m	@25m - noise compressed ³
@ 90% refl.	0.3mm	0.15mm	0.3mm	0.15mm
@ 10% refl.	0.4mm	0.2mm	0.5mm	0.25mm

Typical 0.19mrad (0,011°) (1/e, halfangle)

SD, SDHC[™], SDXC[™]; 32GB card included

Levels each scan: Accuracy 0.015°; Range ± 5°

Via touchscreen display and WLAN

Colour unit

Resolution: HDR: Parallax:

Up to 170 megapixel color High Dynamic Range (HDR) photo recording, 3x / 5x Co-axial design

Deflection unit

Field of view (vertical/horizontal): 300°4 / 360° Step size (vertical/horizontal): Max. vertical scan speed:

0.009° (40,960 3D-Pixel on 360°) / 0,009° (40.960 3D-Pixel on 360°) 5.820rpm or 97Hz

Laser (optical transmitter)

Laser class: Wavelength: Beam divergence: Beam diameter at exit:

Data handling and control

Data storage: Scanner control: New WLAN access: **Multi-Sensor** Dual axis compensator: Height sensor: Compass⁵:

GPS:



Via an electronic barometer the height relative to a fixed point can be detected and added to a scan. The electronic compass gives the scan an orientation. A calibration feature is included. Integrated GPS receiver

Remote control, scan visualisation are possible on mobile devices with Flash® and HTML5

¹ Ranging error is defined as a systematic measurement error at around 10m and 25m, one sigma. Improved compensation available for dedicated mounting (fee-based service). 2 Ranging noise is defined as a standard deviation of values about the best-fit plane for measurement speed of 122,000 points/sec.³ A noise-compression algorithm may be activated thereby compressing raw data noise by a factor of 2 or 4.4 2x150° Homogenous point spacing is not guaranteed. ⁵ Ferromagnetic objects can disturb the earth magnetic field and lead to inaccurate measurements. Subject to change without prior notice

GENERAL

Power supply voltage:

Power consumption:

Battery life: Ambient temperature: Humidity:

19V (external supply) 14.4V (internal battery) 40W and 80W (while battery charges) 4.5 hours 5° - 40°C Non-condensing

Laser class 1

Typical 2.25mm (1/e)

1550nm

Cable connector: Weight: Size: Maintenance / calibration: Located in scanner mount 5.2kg 240 x 200 x 100mm Annual





GSA Contract Holder

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